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Serial Number: 10 | 736,031

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 PALM INTRANETDay : Monday
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Inventor Information for 10/736031

Inventor Name	City	State/Country
BERNINGER, ALWIN	AYSTETTEN	GERMANY

Appln Info	Contents	Petition Info	Atty/Agent Info	Continuity Data	Foreign Data	Inventors
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US 20040260481 A1	20041223	Method for monitoring a machine and such a machine, particularly a robot	702/33		Heiligensetzer, Peter et al.
US 20040143951 A1	20040729	Method and device for positioning components to be joined together	29/428		Berninger, Alwin
US 20020130513 A1	20020919	Wearing ring	285/45		Berninger, Alwin et al.
US 20010023767 A1	20010927	Highly flexible hose end piece	174/480		Berninger, Alwin et al.
US 20010022112 A1	20010920	Device for compensating the weight of a robot arm	74/490.01		Bayer, Albert et al.
US 6761189 B2	20040713	Wearing ring	138/157	138/104; 138/108; 138/110; 138/161; 384/273	Berninger; Alwin et al.
US 6622756 B2	20030923	Highly flexible hose end piece	138/121	138/109; 138/120	Berninger; Alwin et al.
US 6564667 B2	20030520	Device for compensating the weight of a robot arm	74/490.01	267/291; 901/48	Bayer; Albert et al.
US 6352369 B1	20020305	Wearing ring for a cable guidance tube of a robot	384/273	384/297; 384/448	Berninger; Alwin
US 6288512 B1	20010911	Robot with cables extending at least partially on an outside	318/568.1	191/12R; 318/568.11; 318/568.12; 414/680; 414/730; 414/918	Berninger; Alwin et al.
US 6223618 B1	20010501	Device for driving a robot hand	74/490.06	901/29	Berninger; Alwin et al.
US 6189403	20010220	Robot arm	74/490.02	414/918;	Berninger;

B1				901/50	Alwin
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